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Forward Looking Statements

This presentation, as well as other statements made by Aptiv PLC (the “Company”), contain forward-looking statements that reflect, when made, the Company’s current views with respect to current events, certain investments and acquisitions and financial performance. Such forward-looking statements are subject to many risks, uncertainties and factors relating to the Company’s operations and business environment, which may cause the actual results of the Company to be materially different from any future results. All statements that address future operating, financial or business performance or the Company’s strategies or expectations are forward-looking statements. Factors that could cause actual results to differ materially from these forward-looking statements are discussed under the captions “Risk Factors” and “Management’s Discussion and Analysis of Financial Condition and Results of Operations” in the Company’s filings with the Securities and Exchange Commission. New risks and uncertainties arise from time to time, and it is impossible for us to predict these events or how they may affect the Company. It should be remembered that the price of the ordinary shares and any income from them can go down as well as up. The Company disclaims any intention or obligation to update or revise any forward-looking statements, whether as a result of new information, future events and/or otherwise, except as may be required by law.

Urban Mobility CHALLENGES by 2050



+70%

Of Population



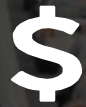
+40%

Freight



5x

Emissions



4x

Cost



3x

Travel time

Source: Arthur D. Little, World Economic Forum, Boston Consulting Group and Aptiv Estimates

BENEFITS of smart mobility automation to cities



87%

Fewer Accidents



28%

Fewer Vehicles



66%

Lower Emissions



44%

Fewer Parking Spaces



30%

Shorter Travel Time

Leveraging Aptiv's Full Capabilities

FLEXIBLE AND SCALABLE APPROACH TO SOFTWARE, RUNNING ON OPTIMIZED VEHICLE ARCHITECTURE

ADVANCED
SOFTWARE



CLOUD

APPLICATION LAYER

MIDDLEWARE

OPERATING SYSTEM

HARDWARE ABSTRACTION

COMPUTE

DATA & POWER
DISTRIBUTION

SENSORS,
PERIPHERALS
& ACTUATORS



MODULAR APPROACH

Flexible software design allows
tailored solution



POLICY & PLANNING

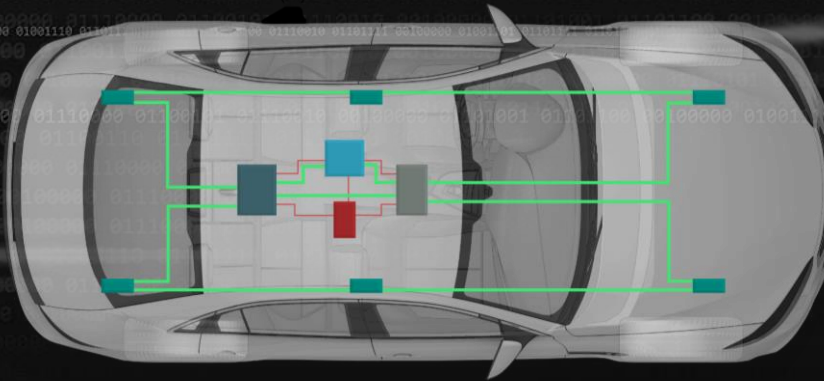
Combined DNA from two full-
stack automated driving teams



LEVEL 1
to
LEVEL 5

SCALABLE PLATFORM

Seamless scalability from Active
Safety to Automated Driving



SMART VEHICLE ARCHITECTURE

Optimized vehicle architectures enabling
fail-operational performance



ADVANCED
ARCHITECTURES

Structured AI Approach

COMBINING THE BEST OF RULES BASED AND AI APPROACHES TO AUTOMATED DRIVING SOFTWARE DEVELOPMENT


EXPLAINABLE


AUDITABLE



LAWS

1. 这只是一个。
2. 测试句子。
3. 我不会说中文

INTERPRETATION



SPECIFICATION



IMPLEMENTATION



BEHAVIOR

START WITH RULES OF THE ROAD

- Rules organized hierarchically with some rules more important than others
- Potential rule violation quantified / weighted with regard to same priority rule

AI FILLS IN CORNER CASES

- Unique situations / cultural norms addressed through applied machine learning
- Avoids exhaustive description of rule combinations / region specific rewrites

Las Vegas Commercial Deployment

DEVELOPING APPROACH THAT ALLOWS APTIV TO QUICKLY AND EFFICIENTLY SCALE FUTURE DEPLOYMENTS



GAINING REAL-WORLD EXPERIENCE

- Deep understanding of support requirements for ongoing operations
- Act as an ambassador for the technology



STANDARD OPERATING PROCEDURES

- Clearly defining value chain roles and responsibilities, key touch points
- Validating commercial model / optimum allocation of trips



SUPPORTING TECH / IP DEVELOPMENT

- Command Center developing teleoperations capabilities
- Demonstrate application / first-use of IP in real-world deployment

50K+

PAID AV RIDES

9 OUT OF 10

WOULD RIDE AGAIN

4.95

STAR USER
RATING OUT OF 5



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Path to Commercialization

CONTINUED PROGRESS, DEPLOYMENT TIMEFRAME REMAINS UNCHANGED

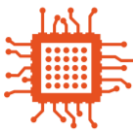
NEXT GENERATION VEHICLE PLATFORM

Vehicle capable of driverless operation



- Modular code structure
- Mobility Cloud integration

- Drive-by-wire interface
- Redundant power brakes and steering gears



- Self actuating doors
- Safety architecture with two redundant safety channels

- Long range radar (3x)
- High def lidar (2x)
- Long range lidar (2x)
- Moderate FOV camera (3x)
- Narrow FOV camera (3x)

- Long range radar (2x)
- High def radar (2x)
- Short range radar (2x)
- Short range lidar
- Fisheye camera

Moderate FOV camera

- Short range radar (2x)
- Long range radar (2x)
- Short range lidar (2x)
- Moderate FOV camera

- Long range radar
- Short range radar
- Short range lidar
- Fisheye camera



Smart City Selection

DEPLOYMENTS EXECUTED ON A SELECTIVE CITY BY CITY BASIS TO MAXIMIZE RETURN ON INVESTMENT

MARKET SELECTION CRITERIA



DEMOGRAPHIC

- Ride Hailing Penetration And Driver Income
- Population Density
- Climate / Weather



OPERATIONAL DOMAIN

- Number Of Vehicles Required
- Traffic Speed, Corner Cases Encountered
- Similarities To Other Deployed Cities



INTANGIBLES

- Market Need / Opportunity To Address Transit Issues
- Alignment To City Strategy / Municipal Buy-In

DEEP UNDERSTANDING OF OPERATIONAL DOMAIN IMPACTS ON CITY DEPLOYABILITY

HARDER

ABILITY TO SERVICE

EASIER

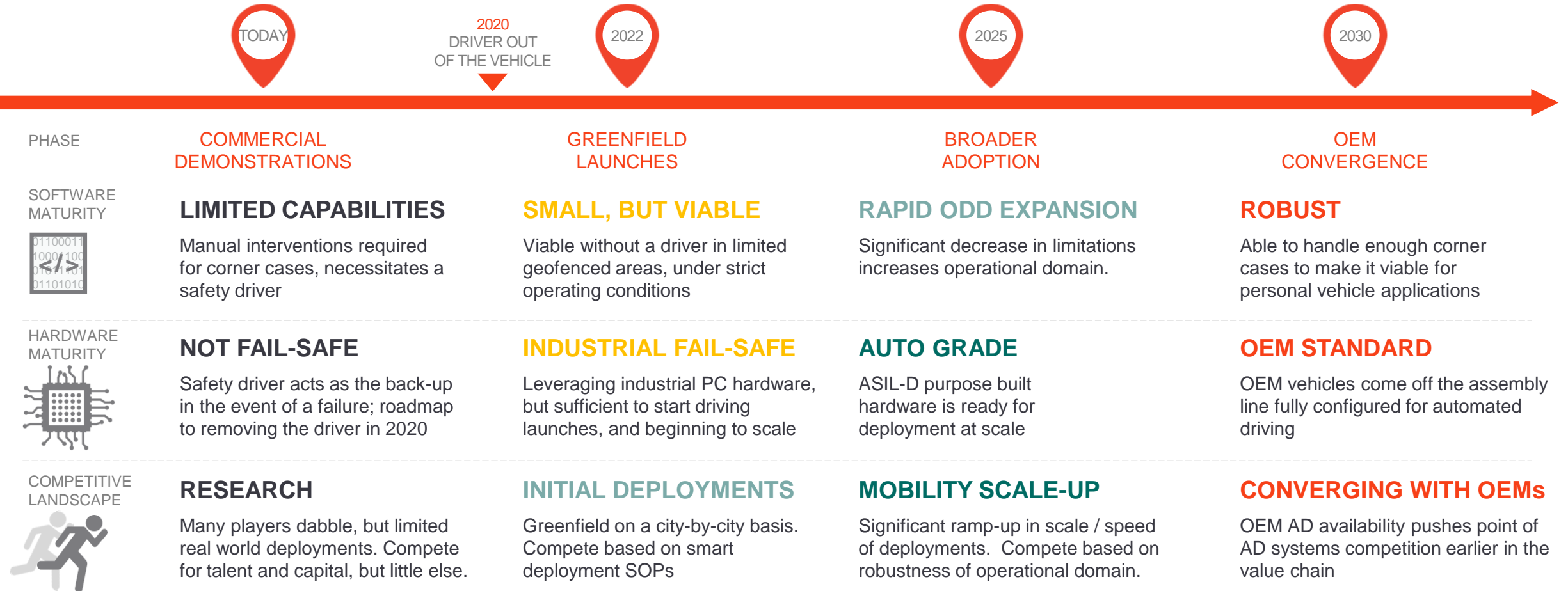
AMoD Requires Four Primary Roles

MOBILITY PROVIDERS NEED APTIV AUTOMATED DRIVING SOLUTIONS



Automated Mobility Deployment Phases

APTIV UNIQUELY POSITIONED FOR SUCCESS ACROSS EACH PHASE OF AD MATURITY



How Aptiv Makes Money

BUSINESS MODEL DRIVES HIGHER MARGIN RECURRING REVENUE

4

DATA MONETIZATION

Enable data acquisition and monetization through edge processing and OTA

3

FLEET MONITORING

Support network operators through AV fleet performance analytic and teleoperations

2

SOFTWARE LICENSING

Autonomous driving stack including upgrades to performance and operational design domain

1

TECHNOLOGY SALE

One-time sale of enabling tech into the vehicle such as sensors, and compute

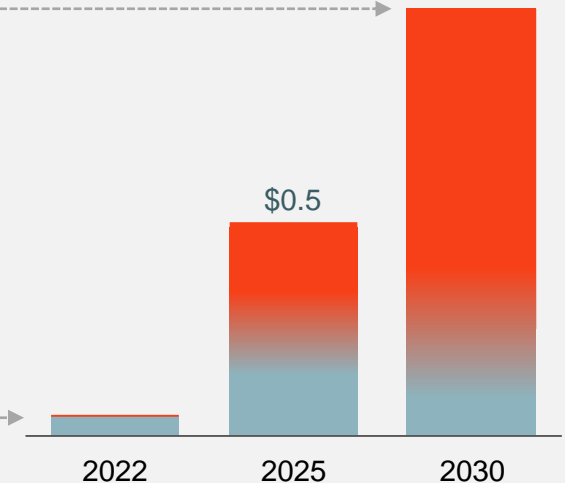


TIME SALE

AMoD REVENUE

70 - 80% RECURRING REVENUE AT SCALE

\$ Billions



Summary

AUTOMATED MOBILITY ON TRACK TO 2025 TARGETS

- Clear strategy for commercialization drives efficient capital deployment, avoids channel conflict
- Deep understanding of operational and regulatory impacts ensures smooth deployments

TECHNOLOGY CAPABILITIES DEVELOPING AS EXPECTED

- 2021 / 2022: Initial launches with mobility providers in geofenced locations
- 2025 - 2030: Improved capabilities, and scale-up of purpose built hardware drives OEM viability

LONGER TERM ROADMAP FOR CONVERGENCE WITH OEMs

- Automated Driving on the spectrum of Active Safety; investments today drive future benefits
- Aptiv's end-to-end solutions enable the commercialization of new mobility



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